
A Study of Efficient Maximum Power Point Tracking Controlling Methods for Photovoltaic System

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Abstract: *The solar photovoltaic is considered to be the one of the most promising energy source in many applications, due to its safety and high reliability. Residential that uses solar power as their alternative power supply will bring benefits to them. In order to increase the efficiency of system during rapid changing environmental conditions; system will adapt some Maximum Power Point Tracking (MPPT) methods. This paper presents a review on various MPPT methods for variable environmental conditions (i.e. variable temperature and irradiation level), their difficulty while tracking and how those difficulties can be overcome efficiently by the other techniques. Apart from all the methods, an open circuit and slope detection tracking technique is found to be an efficient technique with respect to tracking speed and accuracy. This technique can avoid the unnecessary amount of power loss and therefore maintaining the power efficiency.*

Keywords: *MPP (Maximum Power Point), MPPT (Maximum Power Point Tracking), PSoC (Programmable System on Chip), PV (Photovoltaic) panel, Perturb and Observe technique.*

1. INTRODUCTION

In these modern days that consume a lot of energy e.g. fuel-oil, gas, coal etc. that will deplete in its source one day so, much of the focus have been given on the topic of renewable energy. Renewable energies are energy that can be renewed or have no worries of depletion. For instance wind, thermal, bio-mass and solar energy are some of the examples for renewable energy [1]. Solar energy is one of the main renewable energy sources that are widely used in power generating application. Solar energy is an unlimited resource available in nature and set to become important in longer terms for providing heat energy and electricity to the user. This kind of energy resources does not create much pollution as the conventional power sources moreover it has the potential to be the major energy supply in future [1], [8]. In the last decade, there was a consistent development in the worldwide market of photovoltaic (PV) system. By the end of 2008, 13 GW of energy had been generated by the installed PV systems throughout the world. Out of the total system installed 6% were standalone systems, 33% were grid-connected centralized systems, and 61% were grid-connected distributed system. In 2008 alone, photovoltaic systems which generate up to 5.56 GW energy were installed. This represents

the growth in PV systems increased by 1.5 times as compared with the previous year [2].

Solar panels have a nonlinear voltage current (V-I) characteristic with a distinct maximum power point (MPP), which depends on the environmental factors such as temperature and irradiation. In order to continuously harvest maximum power from the solar panels, it is necessary to control optimal impedance between the storage device and PV cell, so that the system can be operated at their Maximum power point (MPP), despite the inevitable changes in the environment. One useful impedance control method is called Maximum Power Point Tracking (MPPT) [3]. The MPPT control is a real time detecting panel output power and adapting the control algorithm to make the system operate under the optimum work state. MPPT control impedance to track the maximum power point by sensing the current and voltage from the PV cell. Now in order to sense current and voltage from panel, MPPT requires additional analog circuits moreover a high speed energy storage device is needed which can accumulate the acquirable maximum power and which changes according to the climate conditions. This requirement can be fulfilled by Programmable system on chip (PSoC)

microcontroller, which reduces the need of separate analog circuits and act as an intelligent MPPT controller [3].

Lead acid battery is used as a quick charging energy storage device. A flexible MPPT controlling is produced for solar energy charging systems by using the combination of PSoC microcontroller and Lead acid battery.

2. REVIEW OF MPPT METHODS

Researchers had found that the efficiency of the PV system can be increased by improving the conversion efficiency of solar cell i.e. an improvement of the solar cell material but this single factor is not enough to get the maximum power at load (Battery), so they developed some maximum power tracking algorithm, where much of the focus has been given on the improvement of power efficiency of the system.

A. Perturb and Observe (P&O) algorithm:

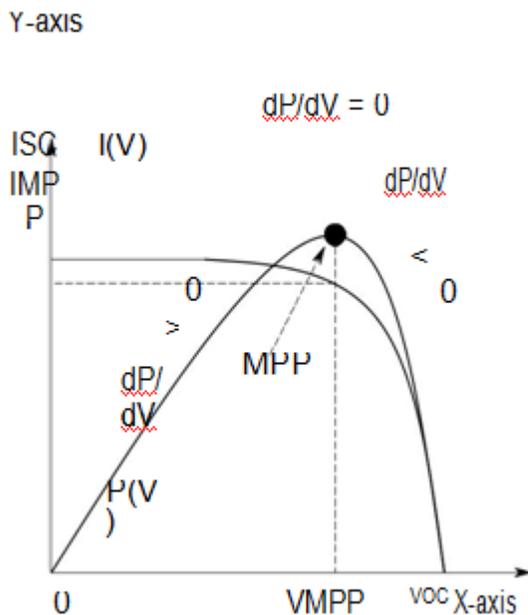


Fig.1. Sign of dP/dV at different position on the power-voltage characteristic of a PV cell. [4], [6]

The Perturb and Observe is one of the so called „hill climbing“ MPPT methods which were developed by F. Iov *et al.* This method is based on the fact that, on the power voltage (P-V) characteristic curve, at the left of MPP the rate of change of power with respect to voltage is greater than zero i.e. $dP/dV > 0$ while at the right, variation becomes less than

zero i.e. $dP/dV < 0$. Fig.1 shows the power voltage (P-V) characteristic curve of Perturb and Observe (P&O) algorithm. As shown in figure, when the operating voltage of the PV panel is perturbed in a given direction and $dP/dV > 0$; it is known that the perturbation moved the panel’s operating point toward the MPP. The P&O algorithm would then continue to perturb the PV panel voltage in the same direction. If $dP/dV < 0$ then the change in operating point moved the PV panel away from the MPP and the P&O algorithm reverses the direction of the perturbation. [4], [5].

B. Incremental Conductance (INC) algorithm:

A similar hill climbing MPPT algorithm is the Incremental Conductance (INC) which was developed by Rosa A. Mastromauro *et al.* This method intends to improve the P&O by replacing the derivative of the power versus voltage dP/dV used by the P&O with the PV panel instantaneous conductance (I/V) and incremental (dI/dV) conductance, according to (1) and (2).

$$\frac{dP}{dV} = \frac{d(V_{pv} I_{pv})}{dV} = I_{pv} + V_{pv} \frac{dI_{pv}}{dV} \quad (1)$$

$$\frac{dV_{pv}}{dV} = \frac{dV_{pv}}{V_{pv}} = \frac{1}{V_{pv}} \quad (2)$$

Where G is the conductance of PV cell and dG is the incremental conductance PV cell. The main objective of this method is to find the distance of PV operating point from the Maximum Power Point and can determine when the MPP has been reached and hence stop the perturbation. At maximum power point, the variation of power with operating point.

C. Modified INC algorithm:

It is one of the MPPT methods, which was developed by Rosa A. Mastromauro *et al.* whose major approach was to improve the PV panel current rather than its voltage. The output of this method, result a current instead of the reference voltage where operating point is adjusted according to solar

panel current. From the power voltage characteristic of PV cell, it is cleared that the variation in panel voltage becomes very slow at right side of the MPP and therefore it is considered to be constant, so between two sampling instance the voltage variation is negligible. As shown in fig.1, the variation in power with PV panel voltage against PV current dP_p provided almost a linear relationship as compare to

its variation against voltage. As the variation $\frac{dP_p}{dV_{pv}}$ is linear, so reference current I_{ref} can be easy to compute which is $\frac{dP_p}{dV_{pv}}$

advantageous over calculation of reference voltage V_{ref} that could have a nonlinear relationship with dP_p . For change dV_{pv}

< 0 , if this condition is satisfied then variation in power with PV panel voltage i.e. $\frac{dP_p}{dV_{pv}}$ is less than zero and $\frac{dP_p}{dV_{pv}}$

reference current must be increased so that operating point move towards MPP. When variation in the PV current i.e.

$\frac{dP_p}{dI_{pv}} > 0$, and reference current must decreased so that operating point move towards MPP. [6]
 $\frac{dP_p}{dI_{pv}} > 0$ then $\frac{dI_{pv}}{dP_p}$

D. Constant Voltage (CV) algorithm:

In order to track the maximum power from PV cell, MPPT controlling uses a Constant Voltage (CV) method. This method was described by Ryoussuke Namba et al. in which maximum power point of the PV panel voltage changes slightly with irradiation. In order to allow the measurement of the open circuit voltage, MPPT momentarily sets the PV panel current to zero. The operating voltage is set to a fixed percentage of the open circuit voltage. The ratio between the open circuit voltage and MPP voltage depends on the solar panel parameters which having a value of 0.76 for commonly used crystalline silicone panel [5, 6]. The overall procedure of this method is divided in to three steps. Firstly the PV panel is disconnected from the battery and measure the open circuit voltage V_{oc} . From the measured voltage V_{oc}

calculate the maximum power point voltage VMPP by using following relation;

$$VMPP = K.V_{oc}$$

Where $K= 0.76$ is the proportionality constant. Now in second stage, the PV panel output voltage V_p can be finding out by connecting it with the battery. Lastly the optimal voltage V_p can be controlled by minimizing the error between VMPP and V_p . For that pulse width modulation technique is used to change the duty cycle ratio such that V_p equals to VMPP. [3]

E. dP-P&O algorithm :

The limitation of the hill climbing algorithm under rapidly changing irradiation is addressed and a simple improvement is proposed called the dP-P&O method which was developed by Dezso Sera et al. This method performs an additional measurement of power in the middle of the MPPT sampling period (T) without any perturbation. As shown in Fig.2, P_k and P_{k+1} are the powers measured at the k and the k+1 sampling instances, dP_1 is the change in power caused by the perturbation of the MPPT and dP_2 be the change in power caused by the increase in irradiation. The change in environmental condition can be shown by change of power between P_X and P_{k+1} reflects as no action has been taken by the MPPT. The changes in environmental condition with slight perturbation of the MPPT will results the change in power dP_1 i.e. power difference P_k . So assuming that over one sampling period of between P_X

MPPT the rate of change in the irradiation is dP caused purely by the MPPT command can be constant, the calculated as;

$$dP = dP_1 - dP_2 = (P_X - P_k) - (P_{k+1} - P_X) = 2P_X - P_{k+1} - P_k$$

The resulting dP reflects the changes due to the perturbation of the MPPT method. [4], [7]

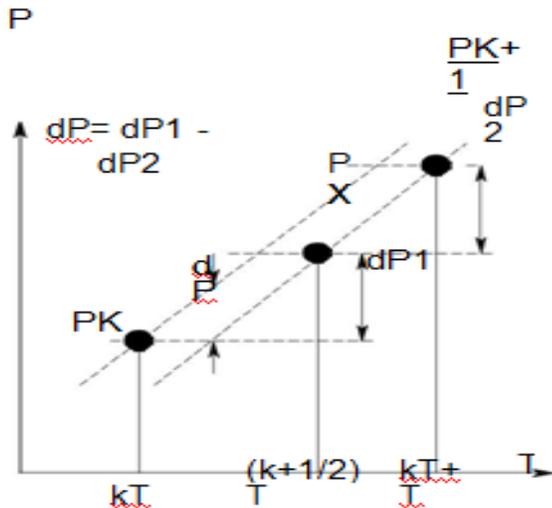


Fig.2. Measurement of the power between two MPPT sampling instances. [7]

F. Open circuit and slope detection tracking algorithm

This algorithm was developed by Chih-Yu Yang et al. which overcomes the drawback of constant voltage algorithm. In this method, solar panel is disconnected from the power stage only at single time i.e.at the beginning of system power ON period. The tracking procedure is divided into three steps, first step involve enabling open circuit tracking to measure open circuit voltage V_{oc} from which PV panel voltage can be calculated by setting it to $0.7 \times V_{oc}$. During open circuit voltage detection period, duty cycle of the boost converter is set to maximum value to increase tracking speed. In second stage slope detection tracking get activated to continuously and accurately track MPP which ensuring that the maximum amount of energy receives at power stage from solar panel. The last stage is for change in environmental condition such that when there was reduction in irradiation level then it means that slope changes from high to low. In such a condition, to increase the total amount of power, slope detection tracking technique increases the switching duty cycle so that PV panel current increases even though operating voltage is reduced. When the irradiation level are increased above the reference value i.e. for an increment in the PV panel operating voltage, then the slope detection tracking decreases the switching duty cycle so that PV panel current get decreased and optimal power produced at the power stage. [1]

A variable step perturbation technique (VSP) is used after the slope detection tracking technique to accelerate tracking

speed and minimizing oscillation problem. It is based on the fact that, when the operating point is far away from the MPP then the system sets larger perturbation step size which increases the tracking speed, while for the operating point closer to MPP, system were chooses smaller step size in order to minimize oscillation around MPP. [1]

3. CLASSIFICATION OF VARIOUS MPPT METHODS

TABLE – I
FEATURES OF VARIOUS MPPT METHODS

Sr. No.	MPPT Algorithm	Features
1	Perturb and Observe (P&O)	<ul style="list-style-type: none"> • Easy to implement and having low computational demand. • Applicable for most of the systems. • Doesn't require any information about the PV panel, but only the measured voltage and current.
2	Incremental Conductance (INC)	<ul style="list-style-type: none"> • Tracking maximum power point without oscillations around the MPP in steady state condition. • Maximum tracking accuracy and faster speed.
3	Modified INC	<ul style="list-style-type: none"> • The main approach is to use a linear relationship between PV current and variation in the PV panel output power with voltage instead of a nonlinear relationship between photovoltaic voltage and variation in the PV panel output power with voltage, so reference current is very easy to calculate than the reference voltage.

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